STATICS



- Vector Mechanics for Engineers: Statics, 9th edition. Ferdinand Beer- E. Russell Johnston Jr. - Phillip Cornwell.
- Engineering Mechanics-Statics, 5th Edition. J. L. Meriam, L. G. Kraige.
- Other Reference: Brain P.Self "Lectures notes on Statics"

Statics of Particles

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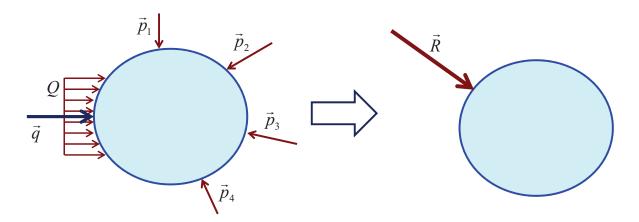
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Statics of Particles

□ Introduction

The objective for the current chapter is to investigate the *effects of forces on particles*.

a) Replacing multiple forces acting on a particle with a single equivalent or *resultant force*.

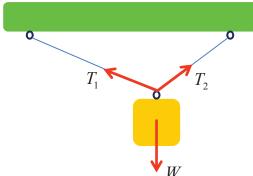


□ Introduction

b) relations between forces acting on a particle that is in a state of *equilibrium*.

$$T_1 = f(W)$$

$$T_2 = g(W)$$



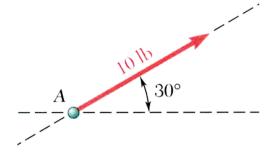
• The focus on *particles* does not imply a restriction to miniscule bodies. Rather, the study is restricted to analyses in which *the size and shape of the bodies is not significant so that all forces may be assumed to be applied at a single point.*

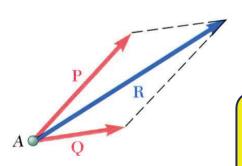
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Statics of Particles

☐ Resultant of Two Forces

- force: action of one body on another; characterized by its *point of application*, *magnitude*, *line of action*, and *sense*.
- Force is a vector quantity.

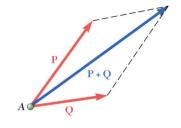




- Experimental evidence shows that the combined effect of two forces may be represented by a *single resultant force*.
- The *resultant* is equivalent to the diagonal of a parallelogram which contains the two forces in adjacent legs.

□ Vectors

• **Vector**: defined as mathematical expressions possessing **magnitude** and **direction** which add according to the parallelogram law. Examples: **displacements**, **velocities**, **accelerations**.



• *Scalar*: parameters possessing magnitude but not direction. Examples: *mass*, *volume*, *temperature*

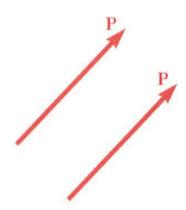
• Vector classifications:

- *Fixed or bound vectors* have well defined points of application that cannot be changed without affecting an analysis. Examples: Reaction Support
- *Free vectors* may be freely moved in space without changing their effect on an analysis. Examples: Couples
- *Sliding vectors* may be applied anywhere along their line of action without affecting an analysis.

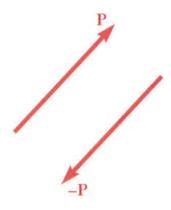
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Statics of Particles

□ Vectors

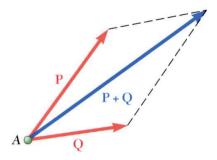


• *Equal vectors* have the same magnitude and direction.

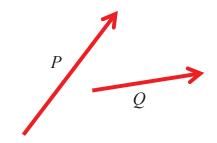


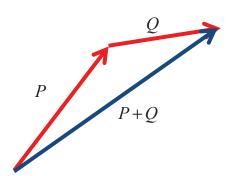
• *Negative vector* of a given vector has the same magnitude and the opposite direction.

- **□** Addition of Vectors
- Trapezoid rule for vector addition



• *Triangle* rule for vector addition

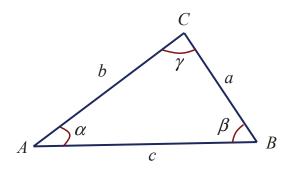




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Statics of Particles

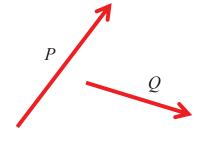
- **□** Addition of Vectors
- Law of cosines,

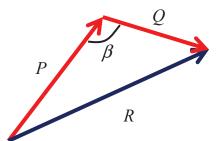


$$c^{2} = a^{2} + b^{2} - 2ab\cos\gamma$$

$$b^{2} = c^{2} + a^{2} - 2ac\cos\beta$$

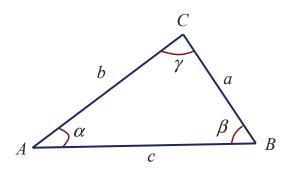
$$a^{2} = b^{2} + c^{2} - 2bc\cos\alpha$$



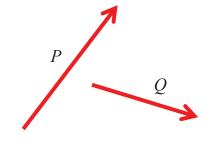


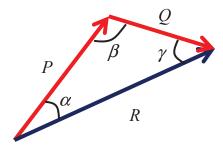
$$R^{2} = P^{2} + Q^{2} - 2PQ\cos B$$
$$\vec{R} = \vec{P} + \vec{Q}$$

- **□** Addition of Vectors
- · Law of sines,



$$\frac{a}{\sin \alpha} = \frac{b}{\sin \beta} = \frac{c}{\sin \gamma}$$





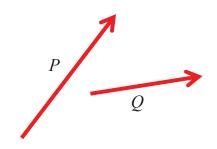
$$\frac{Q}{\sin \alpha} = \frac{R}{\sin \beta} = \frac{P}{\sin \gamma}$$

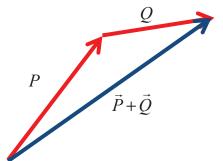
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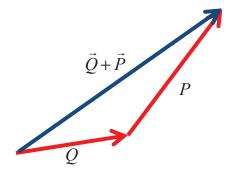
Statics of Particles

- **□** Addition of Vectors
- Vector addition is *commutative*,

$$\vec{P} + \vec{Q} = \vec{Q} + \vec{P}$$





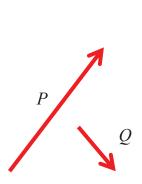


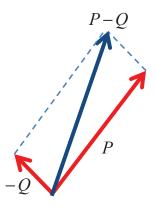
□ Addition of Vectors

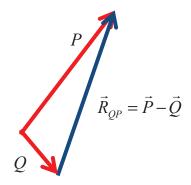
Vector *subtraction*

The subtraction of a vector is defined as the addition of the corresponding negative vector.

$$\vec{P} + (-\vec{Q}) = \vec{P} - \vec{Q}$$







Trapezoid

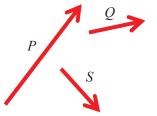
Triangle

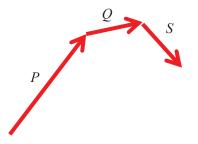
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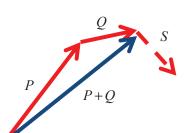
Statics of Particles

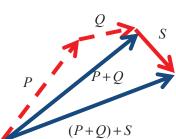
□ Addition of Vectors

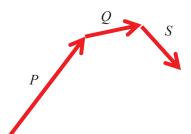
• *Addition of three or more vectors* through repeated application of the triangle rule

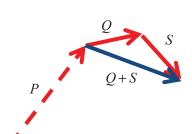


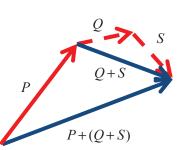






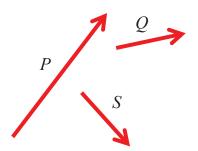


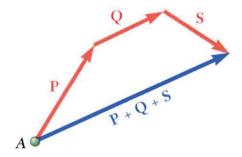




□ Addition of Vectors

• *The polygon rule for the addition* of three or more vectors.





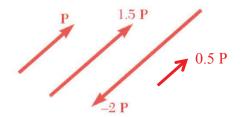
• Vector addition is associative,

$$\vec{P} + \vec{Q} + \vec{S} = (\vec{P} + \vec{Q}) + \vec{S} = \vec{P} + (\vec{Q} + \vec{S})$$

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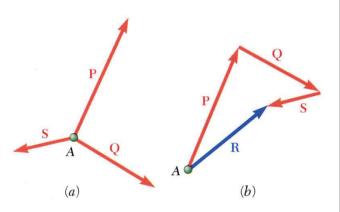
Statics of Particles

- **☐** Resultant of Several Concurrent Forces
- Multiplication of a vector by a scalar



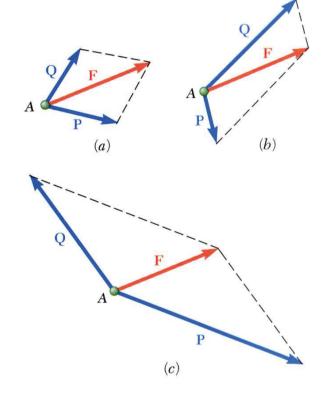
• *Concurrent forces*: set of forces which all pass through the same point.

A set of concurrent forces applied to a particle may be replaced by a single resultant force which is the vector sum of the applied forces.



□ Resolution of a Force into Components

• *Vector force components*: a single force F acting on a particle may be replaced by two or more forces which, together, have the same effect on the particle. These forces are called the *components* of the Original force F, and the process of substituting them for F is called *resolving* the force F into components.



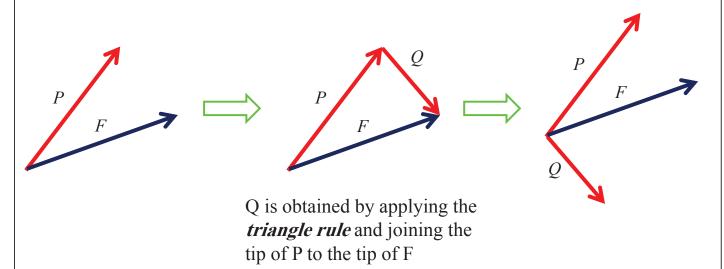
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Statics of Particles

□ Resolution of a Force into Components

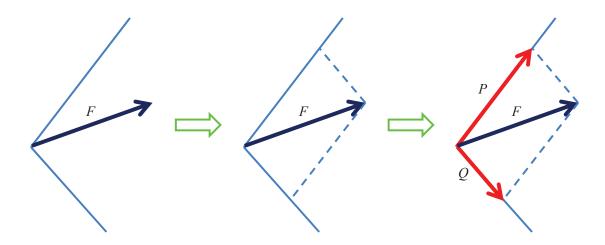
The number of ways in which a given force F may be resolved into two components is **unlimited.** Two cases are of particular interest:

I. One of the Two Components, P, Is Known



□ Resolution of a Force into Components

II. The Line of Action of Each Component Is Known



The magnitude and sense of the components are obtained by applying the *parallelogram law* and drawing lines, through the tip of F , parallel to the given lines of action

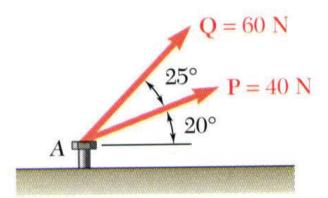
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Statics of Particles

□ Sample Problem 01

The two forces act on a bolt at

A. Determine their resultant.

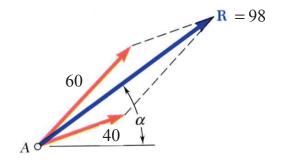


□ Sample Problem 01

SOLUTION: Graphical solution

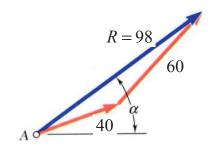
• A *parallelogram* with sides equal to **P** and **Q** is drawn to scale. The magnitude and direction of the resultant or of the diagonal to the parallelogram are measured,

$$\mathbf{R} = 98 \,\mathrm{N}$$
 $\alpha = 35^{\circ}$



• A *triangle* is drawn with **P** and **Q** head-to-tail and to scale. The magnitude and direction of the resultant or of the third side of the triangle are measured,

$$R = 98 \text{ N}$$
 $\alpha = 35^{\circ}$



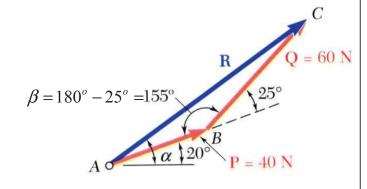
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Statics of Particles

□ Sample Problem 01

SOLUTION: Trigonometric solution

• The Law of Cosines,



$$\Rightarrow$$
 $R = 97.73 (N)$

· The Law of Sines,

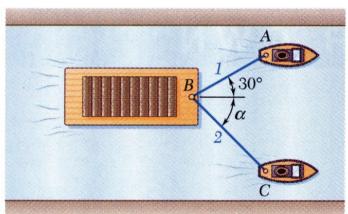
$$\Rightarrow A = 15.04^{\circ}$$

$$\alpha = 35.04^{\circ}$$

□ Sample Problem 02

A barge is pulled by two tugboats. If the resultant of the forces exerted by the tugboats is 5000 lbf directed along the axis of the barge, determine

- a) the tension in each of the ropes for $\alpha = 45^{\circ}$,
- b) the value of α for which the tension in rope 2 is a minimum.



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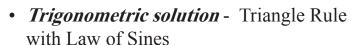
Statics of Particles

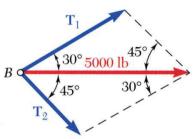
□ Sample Problem 02

SOLUTION:

• *Graphical solution* - Parallelogram Rule with known resultant direction and magnitude, known directions for sides.

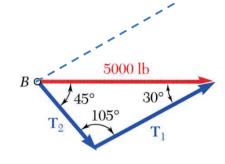
$$T_1 = 3700 \text{ (lbf)}$$
 $T_2 = 2600 \text{ (lbf)}$





 $T_1 = 3660 \text{ (lbf)}$

$$T_2 = 2590 \text{ (lbf)}$$



□ Sample Problem 02

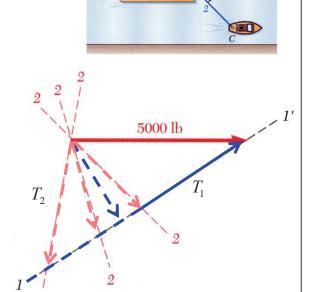
SOLUTION:

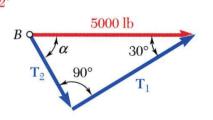
- The angle for minimum tension in rope 2 is determined by applying the Triangle Rule and observing the effect of variations in α
- The minimum tension in rope 2 occurs when T₁ and T₂ are *perpendicular*.

$$T_2 = 2500 \, (lbf)$$

$$T_1 = 4330 \, (lbf)$$

$$\alpha = 60^{\circ}$$





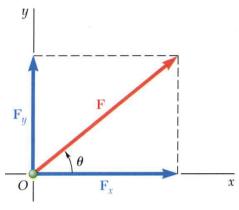
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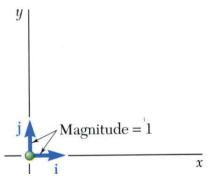
Statics of Particles

- **☐** Rectangular Components of a Force: Unit Vectors
- May resolve a force vector into perpendicular components so that the resulting parallelogram is a rectangle. \vec{F}_x and \vec{F}_y are referred to as **rectangular vector components** and

$$\vec{F} = \vec{F}_x + \vec{F}_y$$

• Define perpendicular *unit vectors* \vec{i} and \vec{j} which are parallel to the *x* and *y* axes.



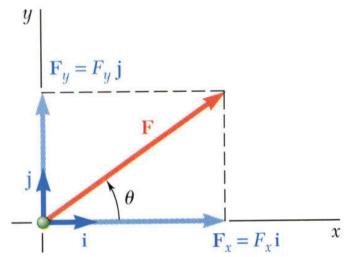


☐ Rectangular Components of a Force: Unit Vectors

 Vector components may be expressed as products of the unit vectors with the scalar magnitudes of the vector components.

$$\vec{F} = F_x \vec{i} + F_y \vec{j}$$

 F_x and F_y are referred to as the *scalar* components of \vec{F}



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Statics of Particles

☐ Addition of Forces by Summing Componen

• Wish to find the resultant of 3 or more concurrent forces.

$$\vec{P} = P_x \vec{i} + P_y \vec{j} \qquad \vec{Q} = Q_x \vec{i} + Q_y \vec{j} \qquad \vec{S} = S_x \vec{i} + S_y \vec{j}$$

$$\vec{R} = \vec{P} + \vec{Q} + \vec{S} = R_x \vec{i} + R_y \vec{j}$$

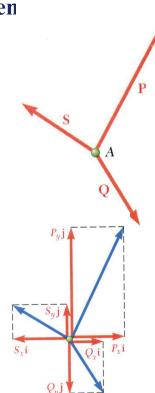
• Resolve each force into rectangular components

$$\vec{R} = R_x \vec{i} + R_y \vec{j} = P_x \vec{i} + P_y \vec{j} + Q_x \vec{i} + Q_y \vec{j} + S_x \vec{i} + S_y \vec{j}$$

$$\Rightarrow \vec{R} = (P_x + Q_x + S_x) \vec{i} + (P_y + Q_y + S_y) \vec{j}$$

$$R_{x} = P_{x} + Q_{x} + S_{x} = \sum F_{x}$$
 $R_{y} = P_{y} + Q_{y} + S_{y} = \sum F_{y}$

$$R_y = P_y + Q_y + S_y = \sum F_y$$



□ Addition of Forces by Summing Components

• The scalar components of the resultant are equal to the sum of the corresponding scalar components of the given forces.

$$\vec{R} = R_x \vec{i} + R_y \vec{j}$$

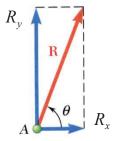
$$R_{x} = \sum_{i=1}^{n} Fx_{i}$$

$$R_{y} = \sum_{i=1}^{n} F y_{i}$$



• To find the resultant magnitude and direction,

$$R = \sqrt{R_x^2 + R_y^2} \quad \& \quad \theta = \tan^{-1} \left(\frac{R_y}{R_x}\right)$$

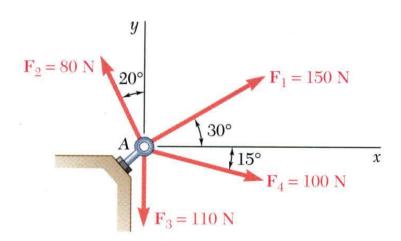


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Statics of Particles

□ Sample Problem 03

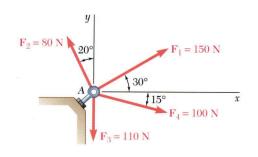
Four forces act on bolt A as shown. Determine the resultant of the force on the bolt.



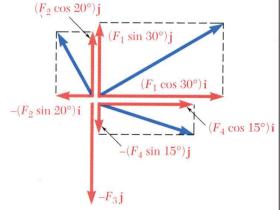
□ Sample Problem 03

SOLUTION:

• Resolve each force into rectangular components.



force	mag	x -comp	y-comp
$\vec{F_1}$			
$ec{F_2}$			
$ec{F_3}$			
$ec{F}_4$			



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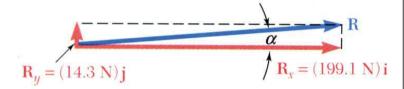
Statics of Particles

□ Sample Problem 03

SOLUTION:

 $F_2 = 80 \text{ N}$ 20° $F_1 = 150 \text{ N}$ 30° $F_4 = 100 \text{ N}$ $F_3 = 110 \text{ N}$

• Calculate the magnitude and direction.

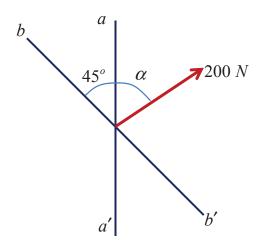


$$R = 199.6 (N)$$

$$\alpha = 4.1^{\circ}$$

□ Sample Problem 04

The 200-N force is to be resolved into components along lines a-a' and b-b'. (a) Determine the angle α using trigonometry knowing that the component along a-a' is to be 150 N. (b) What is the corresponding value of the component along b-b'?

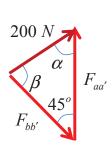


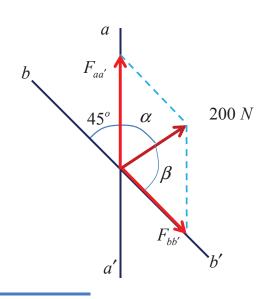
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Statics of Particles

☐ Sample Problem 04

SOLUTION:





$$\beta = 32.03^{\circ}$$

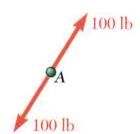
$$\alpha = 102.97^{\circ} \approx 103^{\circ}$$

$$F_{bb'} = 275.63 N$$

□ Equilibrium of a Particle

When the resultant of all forces acting on a particle is zero, the particle is in *equilibrium*.

- *Newton's First Law*. If the resultant force on a particle is zero, the particle will remain at rest or will continue at constant speed in a straight line.
- Particle acted upon by two forces.
 - equal magnitude
 - same line of action
 - opposite sense



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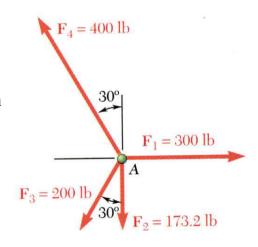
Statics of Particles

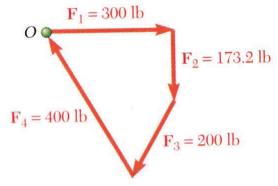
□ Equilibrium of a Particle

- Particle acted upon by three or more forces:
 - graphical solution yields a closed polygon
 - algebraic solution

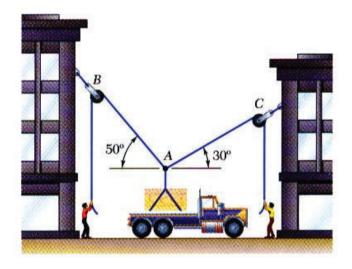
$$\vec{R} = \sum \vec{F} = 0 \implies$$

$$\sum F_x = 0 \quad \& \quad \sum F_y = 0$$

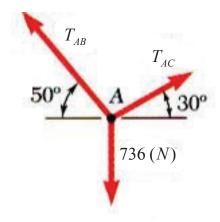




☐ Free-Body Diagrams



Space Diagram: A sketch showing the physical conditions of the problem.



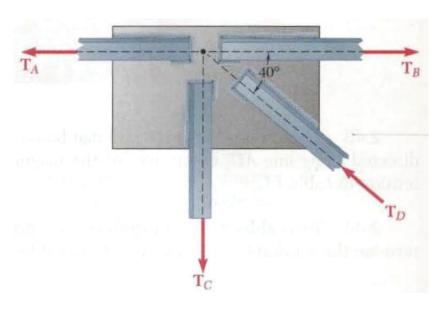
Free-Body Diagram: A sketch showing only the forces on the selected particle.

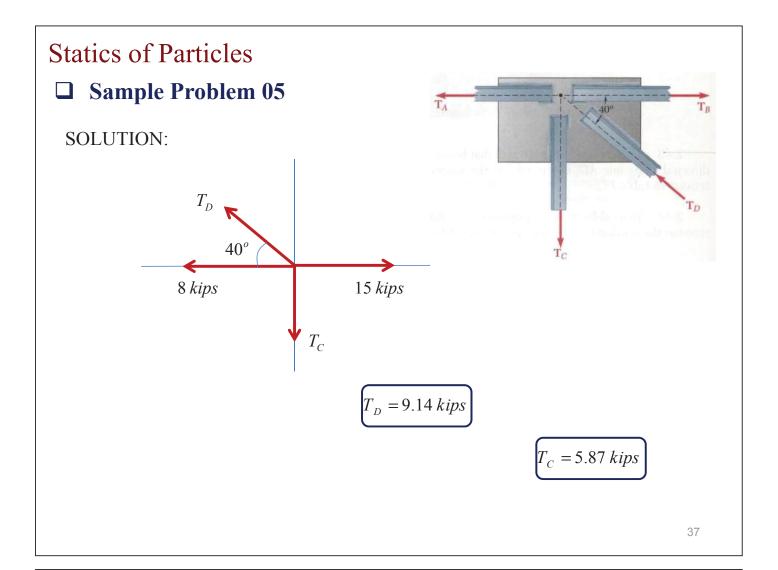
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Statics of Particles

□ Sample Problem 05

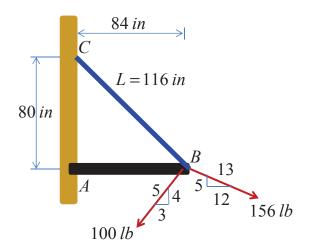
Two forces of magnitude $T_A = 8 \ kips$ and $T_B = 15 \ kips$ are applied as shown to a welded connection. Knowing that the connection is in equilibrium, determine the magnitudes of the forces T_C and T_D .





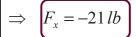
□ Sample Problem 06

Knowing that the tension in cable BC is 145 lb, determine tile resultant of the three forces exerted at point B of beam AB.

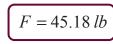


□ Sample Problem 06

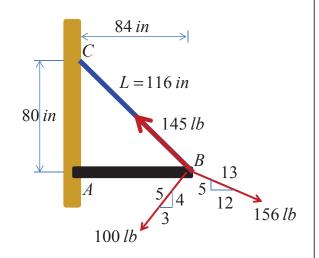
SOLUTION:

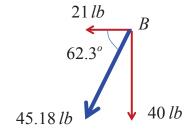


$$\Rightarrow \left[F_y = -40 \ lb \right]$$



$$\theta = 62.3^{\circ}$$



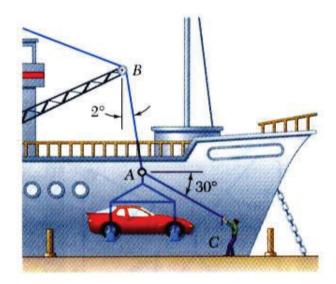


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Statics of Particles

□ Sample Problem 07

In a ship-unloading operation, a 3500-lb automobile is supported by a cable. A rope is tied to the cable and pulled to center the automobile over its intended position. What is the tension in the rope?

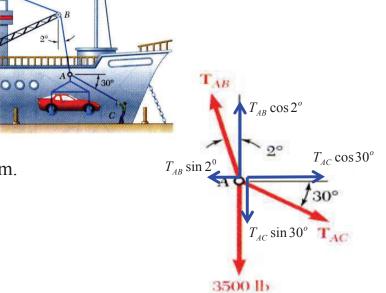


□ Sample Problem 07

SOLUTION:

- Construct a free-body diagram for the particle at *A*.
- Apply the conditions for equilibrium.

$$\left[T_{AC} = T_{AB} \frac{\sin 2^{\circ}}{\cos 30^{\circ}}\right] \qquad (I)$$



$$T_{AB} = 3574.2 (lb)$$

$$T_{AC} = 144 \, (lb)$$

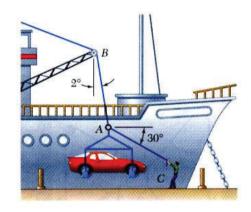
41

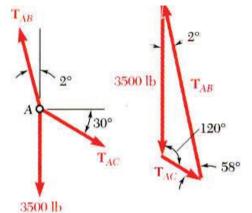
Statics of Particles

□ Sample Problem 07

SOLUTION:

• Alternative solution : Law of sines





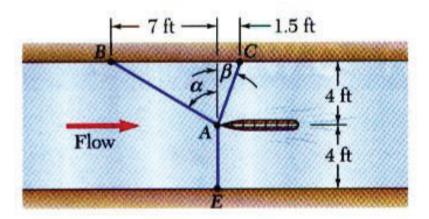
$$T_{AB} = 3574.2 (lb)$$

$$T_{AC} = 144 \, (lb)$$

□ Sample Problem 08

It is desired to determine the drag force at a given speed on a prototype sailboat hull. A model is placed in a test channel and three cables are used to align its bow on the channel centerline. For a given speed, the tension is 40 lb in cable AB and 60 lb in cable AE.

Determine the drag force exerted on the hull and the tension in cable AC.



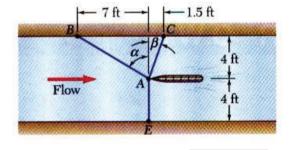
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Statics of Particles

☐ Sample Problem 08

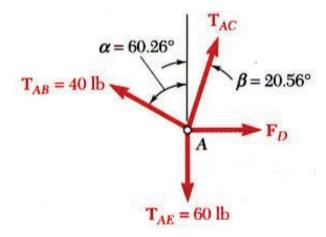
SOLUTION:

• Choosing the hull as the free body, draw a free-body diagram.



 $\alpha = 60.26^{\circ}$

 $\beta = 20.56^{\circ}$



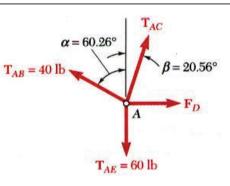
• Express the condition for *equilibrium* for the hull by writing that the sum of all forces must be zero.

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□ Sample Problem 08

SOLUTION:

• Resolve the vector equilibrium equation into two comp equations. Solve for the two unknown cable tensions.



$$\vec{T}_{AB} = -(34.73)\vec{i} + (19.84)\vec{j}$$

$$\vec{T}_{AC} = (0.3512T_{AC})\vec{i} + (0.9363T_{AC})\vec{j}$$

(40 lb)
$$\cos 60.26^{\circ}$$
 j
$$-(40 lb) \sin 60.26^{\circ}$$
 i
$$A F_{D}$$
 i
$$-(60 lb)$$
 j

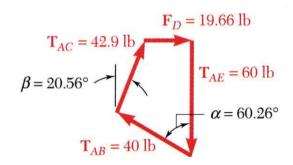
$$\vec{T}_{AE} = -(60)\vec{j} \quad \& \quad \vec{F}_D = F_D\vec{i}$$

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Statics of Particles

□ Sample Problem 08

SOLUTION:



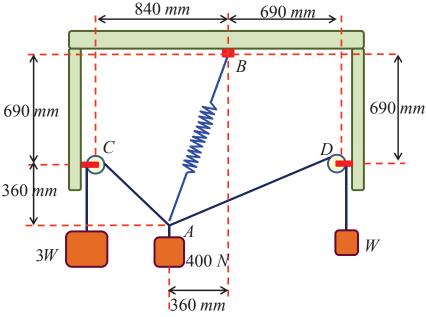
This equation is satisfied only if each component of the resultant is equal to zero

(I) & (II)
$$\Rightarrow$$

$$\begin{cases} T_{AC} = 42.9 \text{ (lb)} \\ F_D = 19.66 \text{ (lb)} \end{cases}$$

□ Sample Problem 09

A load of weight 400 N is suspended from a spring and two cords that are attached to blocks of weights 3W and W as shown. Knowing that the constant of the spring is 800 N/m, determine (a) the value of W, (b) the unstretched length of the spring.



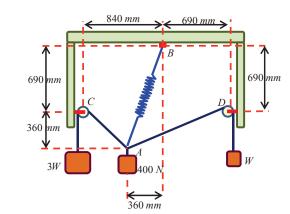
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Statics of Particles

□ Sample Problem 09

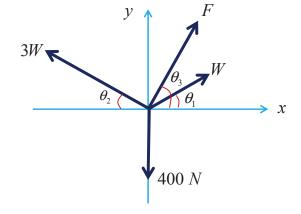
SOLUTION:

draw a free-body diagram.





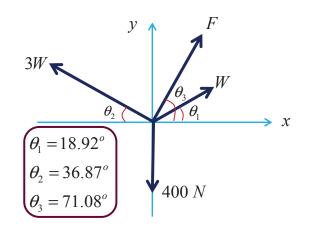
$$\theta_3 = 71.08^{\circ}$$



□ Sample Problem 09

SOLUTION:

Apply the conditions for equilibrium.



$$\Rightarrow \boxed{0.32F - 1.45W = 0} \quad (I)$$

$$\Rightarrow \boxed{0.95F + 2.12W = 400} \quad (II)$$

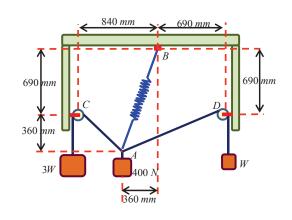
$$(I) & (II) \Rightarrow \begin{cases} W = 62.31(N) \\ F = 282.24(N) \end{cases}$$

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Statics of Particles

□ Sample Problem 09

SOLUTION:



$$\Delta x = 352.8 \, (mm)$$

$$L_1 = 757.20 \ (mm)$$

Unit Vector

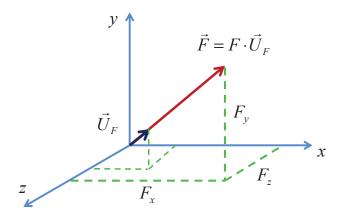
A unit vector is a vector who has the unit length.

$$\vec{F} = F_x \, \vec{i} + F_y \, \vec{j} + F_z \, \vec{k}$$

$$F = \sqrt{{F_x}^2 + {F_y}^2 + {F_z}^2}$$

$$\vec{U}_F = \frac{\vec{F}}{F} \implies \left(\vec{U}_F = \frac{F_x}{F} \vec{i} + \frac{F_y}{F} \vec{j} + \frac{F_z}{F} \vec{k} \right)$$

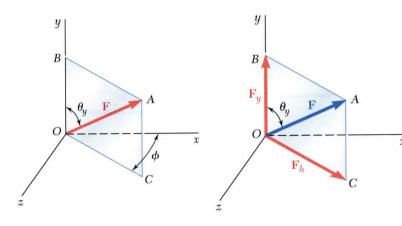
$$U_F = \sqrt{\left(\frac{F_x}{F}\right)^2 + \left(\frac{F_y}{F}\right)^2 + \left(\frac{F_z}{F}\right)^2} = 1$$

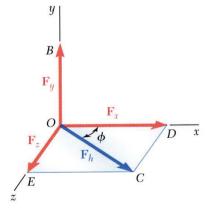


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Statics of Particles

☐ Rectangular Components in Space





- The vector \vec{F} is contained in the plane OBAC.
- Resolve \vec{F} into horizontal and vertical components.

$$F_y = F \cos \theta_y$$

$$F_h = F \sin \theta_y$$

• Resolve F_h into rectangular components

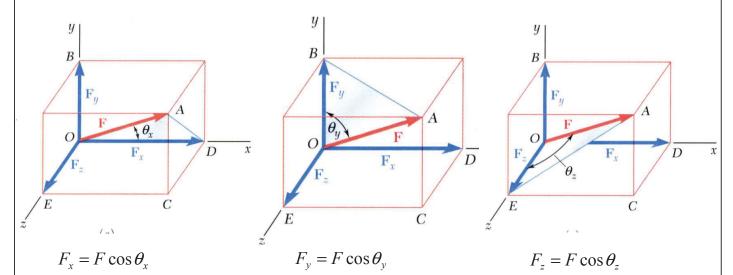
$$F_{y} = F \cos \theta_{y}$$

$$F_{x} = F_{h} \cos \phi \implies F_{x} = F \sin \theta_{y} \cos \phi$$

$$F_{z} = F \sin \theta_{y} \implies F_{z} = F \sin \theta_{y} \sin \phi$$

☐ Rectangular Components in Space

• With the angles between \vec{F} and the axes,



$$\vec{F} = F_x \vec{i} + F_y \vec{j} + F_z \vec{k} \implies \vec{F} = F(\cos\theta_x \vec{i} + \cos\theta_y \vec{j} + \cos\theta_z \vec{k})$$

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Statics of Particles

□ Rectangular Components in Space

• $\vec{\lambda}$ is a unit vector along the line of action of \vec{F} and $\cos \theta_x$, $\cos \theta_y$, and $\cos \theta_z$ are the direction cosines for \vec{F}

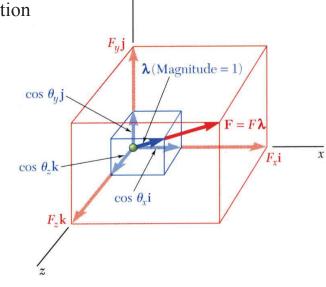
$$\vec{F} = F\vec{\lambda}$$

$$\vec{\lambda} = \cos \theta_x \vec{i} + \cos \theta_y \vec{j} + \cos \theta_z \vec{k}$$

$$\theta_x = \cos^{-1}\left(\frac{F_x}{F}\right)$$

$$\theta_y = \cos^{-1}\left(\frac{F_y}{F}\right)$$

$$\theta_z = \cos^{-1}\left(\frac{F_z}{F}\right)$$

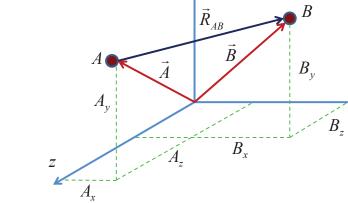


$$\lambda = 1 \implies \left[\cos^2\theta_x + \cos^2\theta_y + \cos^2\theta_z = 1\right]$$

□ Rectangular Components in Space

Direction of the vector is defined by the location of two points,

$$A(A_x, A_y, A_z)$$
 and $B(B_x, B_y, B_z)$



$$\vec{A} = A_x \vec{i} + A_y \vec{j} + A_z \vec{k}$$

$$\vec{B} = B_x \vec{i} + B_y \vec{j} + B_z \vec{k}$$

$$\vec{R}_{AB} = \vec{B} - \vec{A} \implies \vec{R}_{AB} = (B_x - A_x)\vec{i} + (B_y - A_y)\vec{j} + (B_z - A_z)\vec{k}$$

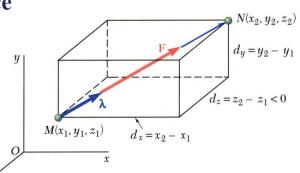
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Statics of Particles

□ Rectangular Components in Space

Direction of the force is defined by the location of two points,

$$M(x_1, y_1, z_1)$$
 and $N(x_2, y_2, z_2)$



vector joining M and N: $\vec{d} = d_x \vec{i} + d_y \vec{j} + d_z \vec{k}$ $d = \sqrt{d_x^2 + d_y^2 + d_z^2}$

$$d_{x} - (x_{2} - x_{1})$$

$$d_{y} = (y_{2} - y_{1})$$

$$d_{z} = (z_{2} - z_{1})$$

$$\vec{\lambda} = \frac{1}{d} (d_x \vec{i} + d_y \vec{j} + d_z \vec{k}) \quad \Rightarrow \quad \vec{F} = F \vec{\lambda}$$

$$\left[F_{x} = \frac{Fd_{x}}{d} \quad F_{y} = \frac{Fd_{y}}{d} \quad F_{z} = \frac{Fd_{z}}{d} \right]$$

□ Addition of n Forces by Summing Components in Space

$$\vec{F}_{1} = Fx_{1} \vec{i} + Fy_{1} \vec{j} + Fz_{1} \vec{k}$$

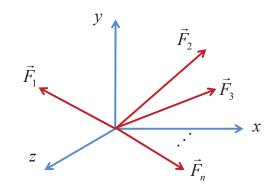
$$\vec{F}_{2} = Fx_{2} \vec{i} + Fy_{2} \vec{j} + Fz_{2} \vec{k}$$

$$\vdots$$

$$\vec{F}_{n} = Fx_{n} \vec{i} + Fy_{n} \vec{j} + Fz_{n} \vec{k}$$

$$\vec{F} = \vec{F}_1 + \vec{F}_2 + \dots + \vec{F}_n$$

$$F = F_1 + F_2 + \dots + F_n$$



$$\Rightarrow \vec{F} = (Fx_1 + Fx_2 + \dots + Fx_n)\vec{i} + (Fy_1 + Fy_2 + \dots + Fy_n)\vec{j} + (Fz_1 + Fz_2 + \dots + Fz_n)\vec{k}$$

$$\Rightarrow \left(\vec{F} = \left(\sum_{r=1}^{n} Fx_r\right) \vec{i} + \left(\sum_{r=1}^{n} Fy_r\right) \vec{j} + \left(\sum_{r=1}^{n} Fz_r\right) \vec{k}\right)$$

$$\Rightarrow \left[F = \sqrt{\left(\sum_{r=1}^{n} Fx_r\right)^2 + \left(\sum_{r=1}^{n} Fy_r\right)^2 + \left(\sum_{r=1}^{n} Fz_r\right)^2} \right]$$

$$\theta_{x} = \cos^{-1}\left(\sum_{r=1}^{n} Fx_{r} / F\right)$$

$$\theta_{y} = \cos^{-1}\left(\sum_{r=1}^{n} Fy_{r} / F\right)$$

$$\theta_{z} = \cos^{-1}\left(\sum_{r=1}^{n} Fz_{r} / F\right)$$

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Statics of Particles

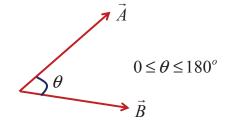
□ Note on Vectors

• Dot or inner product

The dot product is a method for multiplying two vectors. Because the product of the multiplication is a scalar, the dot product is sometimes referred to as the scalar product.

$$\vec{A} \cdot \vec{B} = A \cdot B \cos \theta \implies \theta = \cos^{-1} \left(\frac{\vec{A} \cdot \vec{B}}{A \cdot B} \right)$$

if
$$\vec{A} \cdot \vec{B} = 0 \implies \theta = 90^{\circ} \implies \vec{A} \perp \vec{B}$$



$$\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$$

$$a(\vec{A} \cdot \vec{B}) = (a\vec{A}) \cdot \vec{B} = \vec{A} \cdot (a\vec{B}) = (\vec{A} \cdot \vec{B})a$$

$$\vec{A} \cdot (\vec{B} + \vec{D}) = (\vec{A} \cdot \vec{B}) + (\vec{A} \cdot \vec{D})$$

$$\vec{i} \cdot \vec{j} = \vec{i} \cdot \vec{k} = \vec{k} \cdot \vec{j} = (1) (1) \cos 90^{0} = 0$$

$$\vec{i} \cdot \vec{i} = \vec{j} \cdot \vec{j} = \vec{k} \cdot \vec{k} = (1) (1) \cos 0^{0} = 1$$

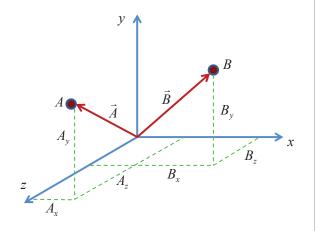
□ Note on Vectors

The dot product to vectors in space

$$\vec{A} = A_x \vec{i} + A_y \vec{j} + A_z \vec{k}$$

$$\vec{B} = B_x \vec{i} + B_y \vec{j} + B_z \vec{k}$$

$$\begin{split} \vec{A} \cdot \vec{B} &= (A_x \, \vec{i} + A_y \, \vec{j} + A_z \, \vec{k}) \cdot (B_x \, \vec{i} + B_y \, \vec{j} + B_z \, \vec{k}) \\ &= A_x B_x (\vec{i} \cdot \vec{i}) + A_x B_y (\vec{i} \cdot \vec{j}) + A_x B_z (\vec{i} \cdot \vec{k}) \\ &+ A_y B_x (\vec{j} \cdot \vec{l}) + A_y B_y (\vec{j} \cdot \vec{j}) + A_y B_z (\vec{j} \cdot \vec{k}) \\ &+ A_z B_x (\vec{k} \cdot \vec{l}) + A_z B_y (\vec{k} \cdot \vec{l}) + A_z B_z (\vec{k} \cdot \vec{k}) \end{split}$$



$$\Rightarrow \vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

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Statics of Particles

□ Note on Vectors

• Projection of a vector on a given axis:

$$P_{OL} = P\cos\theta = \text{projection of } P \text{ along } OL$$

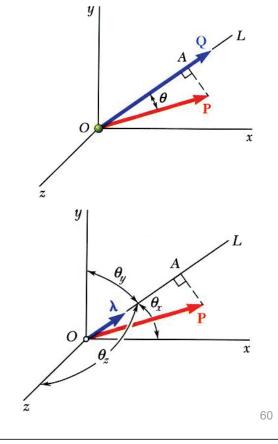
$$\vec{P} \bullet \vec{Q} = PQ\cos\theta$$

$$\frac{\vec{P} \bullet \vec{Q}}{Q} = P\cos\theta = P_{OL}$$

• For an axis defined by a unit vector:

$$P_{OL} = \vec{P} \bullet \vec{\lambda}$$

= $P_x \cos \theta_x + P_y \cos \theta_y + P_z \cos \theta_z$



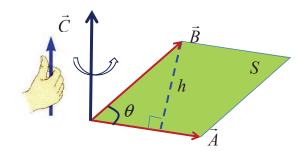
- **□** Note on Vectors
 - The Cross Product (Vector Product)

The cross product $\vec{A} \times \vec{B}$ between two vectors \vec{A} and \vec{B} is a new vector perpendicular to the plane defined by the original two vectors.

$$\vec{C} = \vec{A} \times \vec{B}$$
 , $\vec{C} \perp (\vec{A} \& \vec{B})$

$$C = A \cdot B \sin \theta$$

$$S = h \cdot A = (B \sin \theta) \cdot A \implies C = S$$

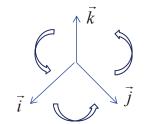


$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$
$$(a\vec{A}) \times \vec{B} = a(\vec{A} \times \vec{B})$$

$$(\vec{A} + \vec{B}) \times \vec{C} = (\vec{A} \times \vec{C}) + (\vec{B} \times \vec{C})$$

$$(\vec{A} \times \vec{B}) \times \vec{C} \neq \vec{A} \times (\vec{B} \times \vec{C})$$

$$\vec{i} \times \vec{j} = \vec{k} \quad \vec{j} \times \vec{k} = \vec{i} \quad \vec{k} \times \vec{i} = \vec{j}$$
$$\vec{i} \times \vec{i} = \vec{j} \times \vec{j} = \vec{k} \times \vec{k} = 0$$



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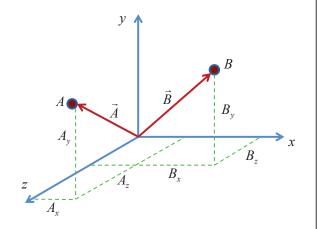
Statics of Particles

□ Note on Vectors

The Cross product to vectors in space

$$\vec{A} = A_x \vec{i} + A_y \vec{j} + A_z \vec{k}$$

$$\vec{B} = B_x \vec{i} + B_y \vec{j} + B_z \vec{k}$$



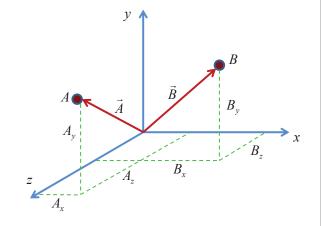
$$\vec{A} \times \vec{B} = (A_x \vec{i} + A_y \vec{j} + A_z \vec{k}) \times (B_x \vec{i} + B_y \vec{j} + B_z \vec{k}) = A_x B_x (\vec{i} \times \vec{l}) + A_x B_y (\vec{i} \times \vec{j}) + A_x B_z (\vec{i} \times \vec{k}) + A_y B_x (\vec{j} \times \vec{i}) + A_y B_z (\vec{j} \times \vec{k}) + A_z B_z (\vec{k} \times \vec{k}) + A_z B_z (\vec{k} \times \vec{k}) + A_z B_z (\vec{k} \times \vec{k})$$

$$\Rightarrow \vec{A} \times \vec{B} = A_x B_y(\vec{k}) + A_x B_z(-\vec{j}) + A_y B_x(-\vec{k}) + A_y B_z(\vec{i}) + A_z B_x(\vec{j}) + A_z B_y(-\vec{i})$$

$$\Rightarrow \vec{A} \times \vec{B} = (A_y B_z - A_z B_y) \vec{i} - (A_x B_z - A_z B_x) \vec{j} + (A_x B_y - A_y B_x) \vec{k}$$

□ Note on Vectors

The Cross product to vectors in space



 $P \times Q$

$$\vec{A} = A_x \vec{i} + A_y \vec{j} + A_z \vec{k}$$

$$\vec{B} = B_x \vec{i} + B_y \vec{j} + B_z \vec{k}$$

$$\Rightarrow \begin{bmatrix} \vec{A} \times \vec{B} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = (A_y B_z - A_z B_y) \vec{i} - (A_x B_z - A_z B_x) \vec{j} + (A_x B_y - A_y B_x) \vec{k}$$

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Statics of Particles

□ Note on Vectors

• Mixed triple product of three vectors,

$$\vec{S} \bullet (\vec{P} \times \vec{Q}) = \text{scalar result}$$

The six mixed triple products formed from S, P, and
 Q have equal magnitudes but not the same sign,

$$\vec{S} \bullet (\vec{P} \times \vec{Q}) = \vec{P} \bullet (\vec{Q} \times \vec{S}) = \vec{Q} \bullet (\vec{S} \times \vec{P})$$
$$= -\vec{S} \bullet (\vec{Q} \times \vec{P}) = -\vec{P} \bullet (\vec{S} \times \vec{Q}) = -\vec{Q} \bullet (\vec{P} \times \vec{S})$$

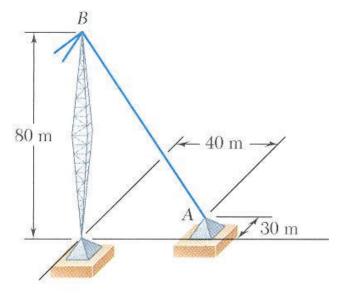
• Evaluating the mixed triple product,

$$\vec{S} \bullet (\vec{P} \times \vec{Q}) = S_x (P_y Q_z - P_z Q_y) + S_y (P_z Q_x - P_x Q_z) + S_z (P_x Q_y - P_y Q_x) = \begin{vmatrix} S_x & S_y & S_z \\ P_x & P_y & P_z \\ Q_x & Q_y & Q_z \end{vmatrix}$$

□ Sample Problem 10

The tension in the guy wire is 2500 N. Determine:

- a) components F_x , F_y , F_z of the force acting on the bolt at A,
- b) the angles θ_x , θ_y , θ_z defining the direction of the force



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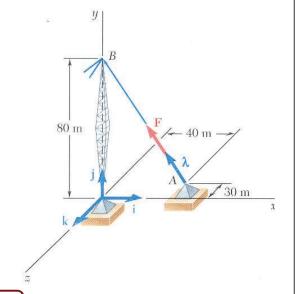
Statics of Particles

□ Sample Problem 10

SOLUTION:

• Determine the unit vector pointing from *A* towards *B*.

$$\overrightarrow{AB} = (-40)\vec{i} + (80)\vec{j} + (30)\vec{k}$$



$$AB = 94.3 \text{ m}$$

• Determine the components of the force.

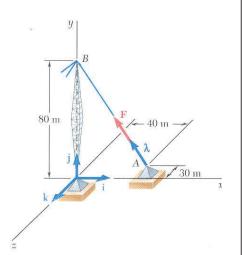
$$\vec{\lambda} = -0.424\vec{i} + 0.848\vec{j} + 0.318\vec{k}$$

$$\vec{F} = (-1060 \,\mathrm{N})\vec{i} + (2120 \,\mathrm{N})\vec{j} + (795 \,\mathrm{N})\vec{k}$$

□ Sample Problem 10

SOLUTION:

• Noting that the components of the unit vector are the direction cosines for the vector, calculate the corresponding angles.



 \rightarrow

$$\theta_x = 115.1^{\circ}$$

$$\theta_y = 32.0^{\circ}$$

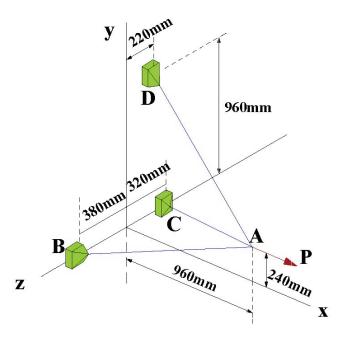
$$\theta_z = 71.5^{\circ}$$

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Statics of Particles

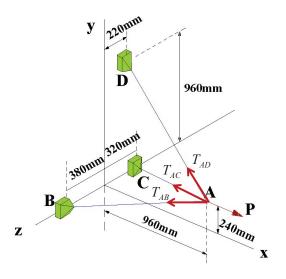
□ Sample Problem 11

Determine the magnitude of P if there is 305 N tension force in Cable AD.



□ Sample Problem 11

SOLUTION:



 $AB = 1060 \, mm$

AC = 1040 mm

 $AD = 1220 \ mm$

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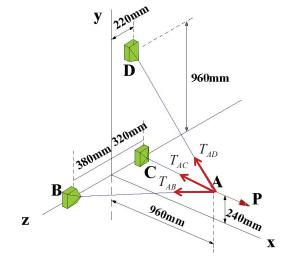
Statics of Particles

□ Sample Problem 11

SOLUTION:

$$\vec{\lambda}_{AC} = \frac{\overrightarrow{AC}}{AC} = -\left(\frac{12}{13}\right)\vec{i} - \left(\frac{3}{13}\right)\vec{j} - \left(\frac{4}{13}\right)\vec{k}$$

$$\vec{\lambda}_{AD} = \frac{\overrightarrow{AD}}{AD} = -\left(\frac{48}{61}\right)\vec{i} + \left(\frac{36}{61}\right)\vec{j} - \left(\frac{11}{61}\right)\vec{k}$$



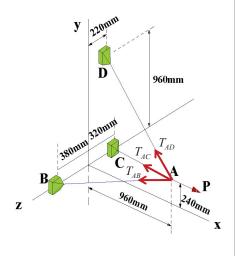
$$\vec{T}_{AC} = \vec{\lambda}_{AC} \cdot T_{AC} = \left(-\frac{12}{13}\vec{i} - \frac{3}{13}\vec{j} - \frac{4}{13}\vec{k} \right) \cdot T_{AC}$$

$$\vec{T}_{AD} = \vec{\lambda}_{AD} \cdot (305) = -240 \,\vec{i} + 180 \,\vec{j} - 55 \,\vec{k}$$
 $\vec{P} = P \,\vec{i}$

□ Sample Problem 11

SOLUTION:

• Apply the conditions for equilibrium.



$$(I), (II), (III) \Rightarrow \begin{cases} T_{AB} = 446.71(N) \\ T_{AC} = 341.71(N) \\ P = 4960(N) \end{cases}$$

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